

## EZM-9950 $96 \times 96$ 1/4 DIN Universal Input Programmable Timer \& Counter with Output Module System

- 6 digits Process (PV) and 6 digits Set (SV) Value Display
- Operation with 2 Set Value
- Reset, Pause and ChA-ChB Counting Inputs
- Configurable Counter / "Totalizer Counter", Batch Counter , Timer, Chronometer , Frequencymeter and Tachometer Functions
- Programmable Time Bases for Timer and Chronometer (Second, Minute , Hour )
- Operation with Automatic and Manual Reset
- Output Module System
- NPN/PNP Type Operation
- INC , DEC , INC / INC , INC / DEC , UP / DOWN , x1 / x2 / x4 Counting with Phase Shifting Property in Counter Function
- Multiplication Coefficient and Decimal Point Position
- Different Alarm Alternatives in Frequencymeter and Cycle Measuring Functions
- Absolute or Offset Operation in Counter Function
- RS-232 (standard) or RS-485 (optional) Serial Communication with Modbus ASCII or RTU Protocol


## ABOUT INSTRUCTION MANUAL

Instruction manual of EZM-9950 Programmable Timer\&Counter consists of two main sections. Explanation of these sections are below. Also, there are other sections which include order information and technical specifications of the device. All titles and page numbers in instruction manual are in "CONTENTS" section. User can reach to any title with section number.

## Installation:

In this section, physical dimensions of the device, panel mounting, electrical wiring, module mounting in the device, physical and electrical installation of the device to the system are explained.

## Operation and Parameters:

In this section, user interface of the device, how to access to the parameters, description of parameters are explained.

Also in these sections, there are warnings to prevent serious injury while doing the physical and electrical mounting or using the device.

Explanation of the symbols which are used in these sections are given below.


This symbol is used for safety warnings. User must pay attention to these warnings.


This symbol is used to determine the dangerous situations as a result of an electric shock. User must pay attention to these warnings definitely.


This symbol is used to determine the important notes about functions and usage of the device.
CONTENTS
1.PREFACE. ..... Page 6
1.1 GENERAL SPECIFICATIONS
1.2 ORDERING INFORMATION
1.3 WARRANTY
1.4 MAINTENANCE
2.INSTALLATION Page 9
2.1 GENERAL DESCRIPTION
2.2 DIMENSIONS
2.3 PANEL CUT-OUT
2.4 ENVIRONMENTAL RATINGS
2.5 PANEL MOUNTING
2.6 INSTALLATION FIXING CLAMP
2.7 REMOVING FROM THE PANEL
2.8 SELECTION OF OPERATION FUNCTION AND INPUT TYPE WITH DIPSWITCH
3.ELECTRICAL WIRINGS ..... Page 15
3.1 TERMINAL LAYOUT AND CONNECTION INSTRUCTION
3.2 ELECTRICAL WIRING DIAGRAM
3.3 CONNECTION OF DEVICE SUPPLY VOLTAGE INPUT
3.4 COUNTING INPUT CONNECTION
3.4.1 PROXIMITY \& SWITCH CONNECTION
3.4.2 INCREMENTAL ENCODER \& SWITCH CONNECTION
3.4.3 SWITCH CONNECTION
3.5 GALVANIC ISOLATION TEST VALUES OF EZM-9950 PROGRAMMABLE TIMER\&COUNTER AND OUTPUT MODULES
4.DEFINITIONS AND SPECIFICATIONS OF OUTPUT MODULES ..... Page 22
4.1 EMO-900 RELAY OUTPUT MODULE
4.2 EMO-910 SSR DRIVER MODULE
4.3 EMO-920 DIGITAL (TRANSISTOR) OUTPUT MODULE
4.4 INSTALLING AND PULLING OUT OUTPUT MODULES
4.5 TO STICK OUTPUT MODULES' LABELS TO THE DEVICE
5.CONNECTION TERMINALS OF OUTPUT MODULES AND CONNECTION WIRING ..... Page 27
5.1 EMO-900 RELAY OUTPUT MODULE CONNECTION
5.2 EMO-910 SSR DRIVER MODULE CONNECTION
5.3 EMO-920 DIGITAL (TRANSISTOR) OUTPUT MODULE CONNECTION
6.CONNECTIONS FOR RS-232 / RS-485 SERIAL COMMUNICATION. ..... Page 296.1 CABLE CONNECTION BETWEEN RS-232 TERMINAL OF THE DEVICEAND PC
6.2 CONNECTION FOR RS-485 SERIAL COMMUNICATION6.3 INSTALLING RS-232 / RS-485 SERIAL COMMUNICATION MODULES TOTHE DEVICE
7.DEFINITION OF FRONT PANEL AND ACCESSING TO THE SET PARAMETERS ..... Page 33
7.1 DEFINITION OF FRONT PANEL7.2 POWER ON OBSERVATION OF EZM - 9950 PROGRAMMABLE TIMER \&COUNTER AND SOFTWARE REVISION ON THE DISPLAY
7.3 ADJUSTMENT OF SET1 AND SET2 VALUES
7.4 RESETTING COUNT VALUE AND OBSERVING TOTAL COUNT VALUE IN COUNTER / "TOTALIZER COUNTER" FUNCTION
7.5 COUNTER / "TOTALIZER COUNTER" PARAMETERS 7.5.1 COUNTER / "TOTALIZER COUNTER" APPLICATIONS EXAMPLES
7.6 BATCH COUNTER PARAMETERS
7.6.1 BATCH COUNTER APPLICATIONS EXAMPLES
7.7 TIME RELAY PARAMETERS
7.7.1 TIMER APPLICATIONS EXAMPLES
7.8 FREQUENCYMETER / TACHOMETER PARAMETERS
7.8.1 FREQUENCYMETER / TACHOMETER APPLICATIONS EXAMPLES
7.9 CHRONOMETER PARAMETERS
7.9.1 CHRONOMETER APPLICATIONS EXAMPLES
7.10 ACCESSING TO THE PROGRAM PARAMETERS
8.PROGRAM PARAMETERS Page ..... 68
9.FAILURE MESSAGES IN EZM-9950 PROGRAMMABLE TIMER \& COUNTER ..... - Page 101
10.SPECIFICATIONS ..... Page 103

Manufacturer Company Name : Emko Elektronik A.S.
Manufacturer Company Address: DOSAB, Karanfil Sokak, No:6, 16369 Bursa, Turkiye
The manufacturer hereby declares that the product conforms to the following standards and conditions.

Product Name : Programmable Timer \& Counter
Model Number : EZM-9950
Type Number : EZM-9950
Product Category : Electrical equipment for measurement, control and laboratory use

Conforms to the following directives :
73 / 23 / EEC The Low Voltage Directive as amended by 93 / 68 / EEC
89 / 336 / EEC The Electromagnetic Compatibility Directive

Has been designed and manufactured according to the following specifications EN 61000-6-4:2001 EMC Generic Emission Standard for the Industrial Environment EN 61000-6-2:2001 EMC Generic Immunity Standard for the Industrial Environment

EN 61010-1:2001 Safety Requirements for electrical equipment for measurement, control and laboratory use

## 1.Preface

EZM Series Programmable Timer \& Counter can be used in package machines, production and quality control rollers, in cutting and processing machine of glass, plastic, marble, sheet, iron, fabric all measuring and controlling of dimension, count, total count, speed, cycle, productivity, time and can be adapted easily to all mechanical construction and automation system. They can be used in many application with their control outputs, serial communication unit and output modules.

Some application fields which they are used are below:

## Application Fields

Glass
Plastic
Marble
Sheet iron
Automative
Machine production industries
1.1 General Specifications


### 1.2 Ordering Information



| A | Supply Voltage |
| :--- | :--- |
| 1 | $100-240 \mathrm{~V} \sim(-15 \% ;+10 \%) 50 / 60 \mathrm{~Hz}$ |
| 2 | $24 \mathrm{~V} \sim(-15 \% ;+10 \%) 50 / 60 \mathrm{~Hz} \quad 24 \mathrm{~V}=--(-15 \% ;+10 \%)$ |
| 6 | $12 \mathrm{~V}=-\mathrm{-}(-15 \% ;+10 \%)$ |
| 9 | Customer $($ Maximum $240 \mathrm{~V} \sim(-15 \% ;+10 \%)) 50 / 60 \mathrm{~Hz}$ |


| D | Serial Communication | Product Code |
| :---: | :--- | :--- |
| 0 | None | - |
| 1 | RS-232 | EMC-900 |
| 2 | RS-485 | EMC-910 |


| FG | Module-1 | Product Code |
| :--- | :--- | :--- |
| 00 | None | - |
| 01 | Relay Output Module | EMO-900 |
| 02 | SSR Driver Output Module | EMO-910 |
| 03 | Digital(Transistor) Output Module | EMO-920 |


| HI | Module-2 | Product Code |
| :--- | :--- | :--- |
| 00 | None | - |
| 01 | Relay Output Module | EMO-900 |
| 02 | SSR Driver Output Module | EMO-910 |
| 03 | Digital(Transistor) Output Module | EMO-920 |


| $\mathbf{U}$ | Function of Device |
| :---: | :--- |
| 0 | Counter / "Totalizer Counter" |
| 1 | Batch Counter |
| 2 | Timer |
| 3 | Frequencymeter and Tachometer |
| 4 | Chronometer |


| $\mathbf{V}$ | Input Type |
| :--- | :--- |
| 0 | NPN |
| 1 | PNP |

All order information of EZM-9950 Programmable Timer\&Counter are given on the table at left. User may form appropriate device configuration from information and codes that at the table and convert it to the ordering codes.

Firstly, supply voltage then output modules and other specifications must be determined. Please fill the order code blanks according to your needs.

Please contact us, if your needs are out of the standards.

~Symbol means Vac, =-Symbol means Vdc二Symbol means Vac and Vdc

### 1.3 Warranty

EMKO Elektronik warrants that the equipment delivered is free from defects in material and workmanship. This warranty is provided for a period of two years. The warranty period starts from the delivery date. This warranty is in force if duty and responsibilities which are determined in warranty document and instruction manual performs by the customer completely.

### 1.4 Maintenance

Repairs should only be performed by trained and specialized personnel. Cut power to the device before accessing internal parts.
Do not clean the case with hydrocarbon-based solvents (Petrol, Trichlorethylene etc.). Use of these solvents can reduce the mechanical reliability of the device. Use a cloth dampened in ethyl alcohol or water to clean the external plastic case.

## 2.Installation



Before beginning installation of this product, please read the instruction manual and warnings below carefully.

In package,

- One piece unit
-Two pieces mounting clamps
- One piece instruction manual

A visual inspection of this product for possible damage occured during shipment is recommended before installation. It is your responsibility to ensure that qualified mechanical and electrical technicians install this product.

If there is danger of serious accident resulting from a failure or defect in this unit, power off the system and separate the electrical connection of the device from the system.

The unit is normally supplied without a power switch or a fuse. Use power switch and fuse as required.

Be sure to use the rated power supply voltage to protect the unit against damage and to prevent failure.

Keep the power off until all of the wiring is completed so that electric shock and trouble with the unit can be prevented.

Never attempt to disassemble, modify or repair this unit. Tampering with the unit may results in malfunction, electric shock or fire.

Do not use the unit in combustible or explosive gaseous atmospheres.
During the equipment is putted in hole on the metal panel while mechanical installation some metal burrs can cause injury on hands, you must be careful.

Montage of the product on a system must be done with it's fixing clamps. Do not do the montage of the device with inappropriate fixing clamp. Be sure that device will not fall while doing the montage.

It is your responsibility if this equipment is used in a manner not specified in this instruction manual.


### 2.2 Dimensions



Maximum 15mm / 0.59 inch

$11.5 \pm 1 \mathrm{~mm} / 0.45$ inch $76 \mathrm{~mm} / 2.99$ inch


### 2.4 Environmental Ratings

## Operating Conditions



Max. Operating Humidity : 90\% Rh (non-condensing)

Altitude : Up to 2000m.


Forbidden Conditions:
Corrosive atmosphere
Explosive atmosphere
Home applications (The unit is only for industrial applications)

### 2.5 Panel Mounting



1-Before mounting the device in your panel, make sure that the cut-out is of the right size.

2-Check front panel gasket position

3-Insert the device through the cut-out. If the mounting clamps are on the unit, put out them before inserting the unit to the panel.


During installation into a metal panel, care should be taken to avoid injury from metal burrs which might be present. The equipment can loosen from vibration and become dislodged if installation parts are not properly tightened. These precautions for the safety of the person who does the panel mounting.


The unit is designed for panel mounting.

1-Insert the unit in the panel cut-out from the front side.

2- Insert the mounting clamps to the holes that located top and bottom sides of device and screw up the fixing screws until the unit completely immobile within the panel


Montage of the unit to a system must be done with it's own fixing clamps. Do not do the montage of the device with inappropriate fixing clamps. Be sure that device will not fall while doing the montage.

### 2.7 Removing from the Panel



Before starting to remove the unit from panel, power off the unit and the related system.


1-Loosen the screws.
2-Pull mounting clamps from top and bottom fixing sockets.

3-Pull the unit through the front side of the panel

### 2.8 Selection of Operation Function and Input Type with DIP Switch



Operation function and input type ( NPN / PNP ) can be changed by DIP switch on the device.


DIP Switch is under cover and cover is on top side of the device Function Selection

| OFF ON |  |
| :--- | :--- |
| 1O |  |
| $2 \square$ | Counter / "Totalizer |
| $3 \square \square$ | Counter" |



Input Type Selection

| OFF ON |  |
| :---: | :--- |
| $\square \square$ | NPN |


| OFF ON |  |
| :--- | :--- |
| $\square \square$ | PNP |

You must ensure that the device is correctly configured for your application. Incorrect configuration could result in damage to the process being controlled, and/or personal injury. It is your responsibility, as the installer, to ensure that the configuration is correct.
Parameters of the device has factory default values. These parameters must be set according to the system's needs.


Only qualified personnel and technicians should work on this equipment. This equipment contains internal circuits with voltage dangerous to human life. There is severe danger for human life in the case of unauthorized intervention.


Be sure to use the rated power supply voltage to protect the unit against damage and to prevent failure.


Keep the power off until all of the wiring is completed so that electric shock and trouble with the unit can be prevented.

### 3.1 Terminal Layout and Connection Instructions




Electrical wiring of the device must be the same as 'Electrical Wiring Diagram' below to prevent damage to the process being controlled and personnel injury.


Optional Output Module Terminals
Relay Output Module
SSR Driver Module Digital (Transistor) Output Module

Supply Voltage Input 100-240V~(-15\%;+10\%) 50/60Hz - 6VA 24 V~(-15\%;+10\%) 50/60Hz - 6VA 24V=-- (-15\%;+10\%) - 6W
$12 \mathrm{~V}=-(-15 \% ;+10 \%)$ - 6W (It must be determined in order)
3.3 Connection of Device Supply Voltage Input

Connection of Universal
Supply Voltage Input


Supply Voltage
100-240 V~(-15\%;+10\%) $50 / 60 \mathrm{~Hz}$

Connection of Low Voltage $24 \mathrm{~V} \sim$ Supply Voltage Input

Connection of Low Voltage 12V $=-$ Supply Voltage Input


Supply Voltage
24 V ~ (-15\%;+10\%) 50/60Hz 12V--- (-15\%;+10\%)
or $24 \mathrm{~V}=-\mathrm{-}(-15 \% ;+10 \%)$

## Note-1 :

There is internal $33 \mathrm{R} \Omega$ fusible flameproof resistor in $100-240 \mathrm{~V} \sim 50 / 60 \mathrm{~Hz}$
There is internal $4 R 7 \Omega$ fusible flameproof resistor in $24 \mathrm{~V} \sim 50 / 60 \mathrm{~Hz}, 24 \mathrm{~V}=-=$ and $12 \mathrm{~V}=-$ Note-2 :
" L " is " + ", " $N$ " is "-" for $24 \mathrm{~V}=-$ supply voltage


Supply voltage range must be determined in order. While installing the unit, supply voltage range must be controlled and appropriate supply voltage must be applied to the unit. Controlling prevents damages in unit and system and possible accidents as a result of incorrect supply voltage.


There is no power switch or fuse on the device. So a power switch and a fuse must be added to the supply voltage input. Power switch and fuse must be put to a place where user can reach easily.


Power switch must be two poled for seperating phase and neutral. On/Off condition of power switch is very important in electrical wiring. On/Off condition of power switch must be signed for preventing the wrong connection.


External fuse must be on phase connection in ~supply input.
External fuse must be on (+) line connection in =-_supply input.

### 3.4 Counting Input Connection

3.4.1 Proximity \& Switch Connection


NOTE-1 : Auxiliary power supply for external transmitter $12 \mathrm{~V}= \pm 10 \%, 50 \mathrm{~mA}$ maximum with short circuit protection


DIP SWITCH ADJUSTMENT : NPN


NOTE-1 : Auxiliary power supply for external transmitter $12 \mathrm{~V}= \pm 10 \%, 50 \mathrm{~mA}$ maximum short circuit protection


DIP SWITCH ADJUSTMENT : NPN


NOTE-1 : Auxiliary power supply for external transmitter $12 \mathrm{~V}= \pm \mathbf{1 0} \%, 50 \mathrm{~mA}$ maximum short circuit protection
3.5 Galvanic Isolation Test Results of EZM-9950 Programmable Timer \& Counter and Output Modules


## 4. Definitions and Specifications of Output Modules

EZM-9950 programmable Timer \&Counter is a modular product which is designed to operate with additional output units which user may need.

Two output modules can be plugged in the equipment by the user. User may configure the product for different applications according to the system requirements with the output modules which are described in this section.

## Dimensions of Output Modules



### 4.1 EMO-900 Relay Output Module

EMO-900 Relay output module can be plugged in Module-1 or Module-2 socket to be used in applications that relay output is necessary

Specifications of EMO-900 Relay Output Module
Output :5A @ 250V~, Single Open / Close Contact
Dimensions : $18 \times 75.2 \times 41.4 \mathrm{~mm}$
Electrical Life : 100.000 operation (Full Load)

## Applications of EMO-900 Relay Output Module

It can be used for programmable different alarm functions as control or alarm output.

### 4.2 EMO-910 SSR Driver Module

EMO-910 SSR Driver Module can be plugged in Module-1 or Module-2 socket to be used in applications that SSR driver output is necessary

## Specification of EMO-910 SSR Driver Module

Output : Maximum $20 \mathrm{~mA}, 15-18 \mathrm{~V}= \pm 10 \%$, isolated
Dimensions: $18 \times 75.2 \times 41.4 \mathrm{~mm}$

## Applications of EMO-910 SSR Driver Module

It can be used for programmable different alarm functions as control or alarm output.
Note 1: SSR Driver Module must be preferred instead of relay output module in applications with short output period because of limited life of their relay contact (number of open/close events).

### 4.3 EMO-920 Digital (Transistor) Output Module

EMO-920 Digital (Transistor) Output Module can be plugged in Module-1 or Module-2 socket to be used in applications that digital output is necessary

Specifications of EMO-920 Digital (Transistor) Output Module
Output : Maximum $40 \mathrm{~mA}, 15-18 \mathrm{~V}= - \pm 10 \%$, isolated
Dimensions: 18x75.2x41.4mm
Applications of EMO-920 Digital (Transistor) Output Module
It can be used for programmable different alarm functions as control or alarm output.

### 4.4 Installing and Pulling Out Output Modules



First, detach all cable connections from the device and uninstall it from the panel.


Pull the cover case with your other hand from front panel to rear side.


Pull out the cover case from the device


Slide output modules into socket.
Pull out the module from it's socket, instead of this module install the new one or other module user wants to use.


Replace the cover case by taking care of the terminal numbers should be at right position.


After adding or changing modules to the unit, these changes must be taken into consideration while mounting of the unit to the system. If mounting is incorrect, it can cause accidents to harm system, operator or person who does the mounting. Responsibility of these kind of harmful events belongs to the user.

### 4.5 To Stick Output Modules' Labels to the Equipment

Every module which is plugged in Module-1 or Module-2 socket has labels' for showing the relation between connection terminal and the device. These labels are attached to empty attachment places which are separated for Module-1 and Module-2 on the device. Labels for all modules and attachment places are shown below.

Label which is plugged in Module-2 socket, describes module termination connection is attached to this area.


Label which is plugged in Module-1 socket, describes module termination connection is attached to this area.

## LABELS FOR OUTPUT MODULES

Label for EMO-900 Relay Output Module

Label for EMO-910 SSR Driver Module

Label for EMO-920 Digital (Transistor) Output Module

Example : If user installs EMO-900 Relay Output Module to Module-1 socket, EMO-910 SSR Output Module to Module-2 socket and attach the appropriate labels on the device view will be like below:


## 5.Connection Terminals of Output Modules and Connection Wirings

Module-1 / Module-2 Optional Output Modules


### 5.1 EMO-900 Relay Output Module Connection



Fuses must be selected according to the applications.


Fuses must be selected according to the applications.
5.3 EMO-920 Digital (Transistor) Output Module Connection


RS-232 Terminal Definitions


RS-485 Terminal Definitions


EZM-9950

## PC (Personal Computer)

## 9 Pin DCON connection



PC (Personal Computer)
EZM-9950
25 Pin DCON connection

6.2 Connection for RS-485 Serial Communication

PC(Personal Computer)


RS-232 $\Rightarrow$ RS-485
Convertor


MASTER

32 terminal can be connected in RS485 line

Rt resistor $=120 \Omega$
For communication connection
Twisted Pair cable must be used
Cable lenght can be maximum 1000 meters in 9600 baud rate.

When baud rate increases, cable lenght must decrease.


SLAVE-2


SLAVE-N


### 6.3 Installing RS-232 / RS-485 Serial Communication Modules to the Device

Pull the cover case with your hand through rear side as explained in "Installing and Pulling Out Output Modules" section. Pull the modules in Module-1 and Module-2 socket through rear side. Separate supply card which is at the bottom of the equipment by lifting the locking tabs located on front panel. Pay attention to cable connection between top and bottom cards. Damages in this cable makes the equipment not to work.

RS-232 or RS-485 module is plugged into socket signed as $A$ and $B$. Hold the equipment to be it's front panel is on your right, communication socket is on your left and module connection socket with 5 terminals on above. Plug in module connection socket with 5 terminals to the socket on Top Card. Do the same things for terminal socket in bottom card and connection socket with 3 terminals. Plug in bottom card to the place in front panel. Install the modules which are pulled out to Module-1 and Module-2 socket. Replace the cover case by taking care of the terminal numbers should be at right position.


## 7.Definition of Front Panel and Accessing to the Set Parameters

7.1 Definition of Front Panel


NOTE-2 INCREMENT Button:
It is used for increasing the value which is selected with shifting button.
( The value can be adjusted with increment button from 0 to 9 )

NOTE-1 : Total count value is 12 digits in Counter / "Totalizer Counter" function
NOTE-2 : In Counter / "Totalizer Counter" function if SET1 operation form selection parameter Pro-2] is DEDSD 1 , then SET1 can be negative. While most significant digit ( 6 th digit ) of SET1 value is changed from 0 to 9 with increment button, after 9, "-" character is shown. If when "-" character is on the most significant digit ( 6th digit ) of SET1 value and Enter button is pressed, SET1 value becomes negative.

### 7.2 Power On Observation of EZM - 9950 Programmable Timer \& Counter and Software Revision on the Display

When power is applied to the device, software revision number of the controller is momentarily illuminated on actual value display. Then operation screen is observed.

When power on, view of the screen is shown below:



Software Revision


Operation Screen is shown
7.3 Adjustment of SET1 and SET2 Values

Changing SET2 value in Counter /‘Totalizer Counter" functions


When shift button is pressed, 6th digit of SET2 value starts to flash.

Press SET1 or SET2 button to exit without saving Set value.


Save the value as SET2 value by pressing Enter button.

If Pra-2B Reset and Set Protection parameter is DODCD2, DODNO3 or 0 DOU5then SET2 value can not be changed. For details, refer to parameters section.


Save the value as SET1 value by pressing Enter button. 000054 , then SET1 value can not be changed. For details, refer to parameters section.
7.4 Resetting Count Value and Observing Total Count Value in COUNTER / "TOTALIZER COUNTER" Function


Count value is reset and added to the total count value when RESET button is pressed.


Continue to press TOTAL button. When user stops pressing Total button, operation screen is shown.

Total count value is $\mathbf{1 2}$ digits.
When user stops pressing the buttons, operation screen is shown.

Note-1: If manual reset is applied when counting direction parameter Pra-i? Is DOUDDi difference between SET2 value and value on the screen is added to the total count value


## Operation Screen

Note-2: Becoming zero of count value is for if counting direction parameter $P_{r a-19}$ Is DCDED direction parameter Pra-19 Is SODED 1 count value becomes equal to SET2 value

If Pro-2B Reset and Set Protection parameter is 0000 i or 0 total count value can not be reset. For details, refer to parameters section.

RESET operation can be realized by Reset button or applying signal to the RESET input. These two operations are named MANUAL RESET in parameters section. At the end of the MANUAL RESET operation, if counting direction parameter Pra-19 is DODODS then count value becomes ODODOD . If counting direction parameter Pra-19 is DOD OD then count value becomes equal to SET2 value .


7．5 COUNTER／＂TOTALIZER COUNTER＂Parameters
SET1
SET value for Output－1．Control of the Output－1 is done according to this value．It can be adjusted from DRDOD to 939398

If SET1 operation form selection parameter $\operatorname{Pro-2}$ ？is selected operation with offset DODOD i，it can be adjusted from－99393to 939398

## SET2

SET value for Output－2．Control of the Output－2 is done according to this value．It can be adjusted from DODNDD to 999938

## Pro－0：

Input Types and Functions

Upcount on rising edge of Ch－A input（INC）
Gロ～円7
Downcount on rising edge of Ch－A input（DEC）
000002
Upcount on rising edge of Ch－A input and downcount on rising edge of Ch－B input（INC／DEC）
ODODZ3 Upcount on rising edge of Ch－A and Ch－B inputs（INC／INC）
DПППU Upcount on rising edge of Ch－A input when Ch－B is at 0 ，downcount on rising edge of Ch－A input when Ch－B is at 1．（UP／DOWN）

OИON二 $x 2$ phase shifting（for incremental encoders）


## $P_{\Gamma ロ}-\square^{4}$ Pulse Time for $\mathrm{Ch}-\mathrm{A}$ and $\mathrm{Ch}-\mathrm{B}$ Inputs

It is used not to evaluate the false signals by electrical noise or the signal that is less than the determined pulse time．
It can be adjusted from 802000 to 020250

## ローローム曰 Output Functions

ODODO Manual Reset－1．Device continues to count till manual reset is applied． Output－2 pulse time $P_{r a^{-}} 17$ is not considered．

OИODO 1 Manual Reset－2．Device continues to count till count value reaches to SET2 value．For starting to count again，manual reset input must be active．Output－ 2 pulse time Pro－17 is not considered．

ODODOD Manual Reset－3．It operates like Manual Reset－1．Only difference，output－2 pulse time Pra－17 is considered．
ONODO3 Automatic Reset－1．Count value is reset when it reaches to SET2 value（For $0 \Rightarrow P)$ ．Count value is added to total count value and device starts to count from SODODS

In operation with Manual or Automatic Reset，at the end of the reset operation，if
 becomes

For details on parameters，refer to Section 8 （Program Parameters）．

ODOD, Automatic Reset-2. Counting is stopped when count value reaches to SET2 value. Count value becomes zero (for $0 \Rightarrow P$ ) at the end of output-2 pulse time Pro-17 And count value is added to total count value. Device starts to count from BNDODC
ONOD5 Automatic Reset-3. Count value becomes zero (for $0 \Rightarrow P$ ) when it reaches to SET2 value and count value is added to total count value. Device starts to count from ODODOD . Meanwhile, SET2 value is shown in actual value display, count value is shown at the end of output-2 pulse time Pro-17

ODOD5 Automatic Reset-4. Counting is continued when count value reaches to SET2 value. Count value becomes zero (for $0 \Rightarrow P$ ) at the end of Output-2 pulse Pro-17 time and it is added to total count value. Device starts to count from ODODOD
 1 and Output-2 pulse times (Pro-15 and Pra-17) are not considered. It is preferred if upcount and downcount are done at the same time.

In operation with Manual or Automatic Reset, at the end of the reset operation, if counting direction parameter $P_{r a}-19$ is 020000 ( $0 \Rightarrow P$ ), count value


## Pro- 14

Operation form for Output-1
ODODNO Output-1 Normally non-energised

$\square \Gamma \square-15$ Operation form for Output-2
BNOD二त Output-2 Normally non-energised
OИOU, 1 Output-2 Normally energised


Output-1 Pulse Time
Energising time for Output-1. It can be adjusted from DODNDD to 059393 If it is $\triangle D D D O$, then it operates indefinitely.


Output-2 Pulse Time
Energising time for Output-2. It can be adjusted from DODEDO to 003939 If it is DUDUD , then it operates indefinitely.

## $\square \square_{1}-1 \square$


Upcount( $0 \Rightarrow$ Preset)
BNANA
Downcount(Preset $\Rightarrow 0$ )

## $\square \Gamma \square-\beth \square$ Point Position for display


OПOD二 1 Between first and second digits
ODGDD르 Between second and third digits
ODODZ3 Between third and fourth digits
ODODU Between fourth and fifth digits
$\square ロ$ ローロ
ARASNS Count value is saved to memory when power is off and restored on power up．
ODNDG 1 Count value is not saved to memory when power is off

## ローローコロ Selection of SET1 Operation Form



ORONT Operating with offset．SET1 can be adjusted SET1＝SET2＋SET1

## Pro－23 Slave Adross

Device address for serial communication bus． It can be adjusted from DODND to 020247

## $\square \boldsymbol{\square} \square-\square$ Selection of Modbus Protocol Type

ONOD，MODBUSASCII communication protocol is selected．
OИOD， 1 MODBUS RTU communication protocol is selected
ローローム』 Parity
DAODOS No parity
OИOИИ Odd parity
ロNOD Even parity

## ローローコロ Baud Rate

DOD二口丂 1200 Baud Rate
믄 2400 Baud Rate
ODOD二ㄹ 4800 Baud Rate
OロO～J3 9600 Baud Rate
ONOUT4 19200 Baud Rate
i For details on parameters，refer to Section 8 （Program Parameters）．

$$
\begin{array}{rl}
\boxed{\square-ロ ー ム \square} & \text { Stop Bit } \\
\square \square \square \square \square \square & \text { 1 Stop Bit } \\
\square \square \square \square \square ~ & 2 \text { Stop Bits }
\end{array}
$$

## $\square \square \square-\square \square$ Reset and Set protection（Accessing from front panel）

ONODS There is no Reset and Set protection
OИODन 1 Reset Button protection is active
ONONZㄹ SET1 and SET2 protection is active
ODND二3 Reset Button，SET1 and SET2 protection is active（Full protection）
ODODДU SET1 protection is active
ODOD5 SET2 protection is active

## $\square_{\Gamma ロ ー ヨ 凸}$ Multiplication Coefficient

Count value is multiplied with this value．It can be adjusted from $\square 205 \mathrm{Dt}$ to． 993939 If it is iD ODS，it has no effect．

## $\square ロ \square-\square \square$ Program Password

It is used for accessing to the program parameters．
It can be adjusted from 000005 to 093993 ．If it is 00000 ，there is no password protection．

### 7.5.1 COUNTER / "TOTALIZER COUNTER" Applications Examples

## EXAMPLE-1:

There is a production band like in diagram below. Bottles are perceived by a proximity sensor in Ch-A. If Pra-Di 0 DODOD ; Pra-30 $=0$ IDODO ;


Counting the bottles is done with upcount by using only ChA input. When user reset count value with manual reset, count value is added to total count value.

## EXAMPLE-2:

There is a cloth workbench. An encoder with 100 pulse is connected to this system. The encoder is connected to Ch-A and Ch-B inputs.


Ch-A and Ch-B




You wish to display 200 in actual value display for a drive pulley going forward of 100 cm . If you want to display cloth length in actual value display, you must adjust coefficient parameter Pro-3D like in below:

Pro-30 $=\frac{\text { Measured cloth length }}{\text { Value on the screen }}$
Pro-30 Coefficient must be $=100 / 200=" 00.5000 "$
After adjustment of coefficient, calculated value is cloth length and you can see this value in actual value display.

If you want to display the speed of the drive pulley as dm instead of $\mathrm{cmPra-2D}$ point position for


## EXAMPLE-3:

There is a system like in the diagram below. Ch-A is used for measuring the flow.
If
Pra-Di= DODODO Pra-30 $=0$ IDODD
In this application, total amount of flow is measured. If it is
 known how many pulses are being sent for each liter from the sensor in Ch-A we can measure the desired value by changing the Pro-30 parameter.
For example if sensor gives 10 pulses for 1 liter fluid flow and we want to observe the liquid quantity as liter, coefficient parameter Pro-30] parameter value must be Pro-30 $=1 \mathrm{Lt} / 10$ pulse $=$ "00.1000"

## EXAMPLE-4:

There is a cutting unit below. 100-pulse encoder is connected to Ch-Aand Ch-B inputs.


Pra-22=00000i And Pra-30 = 0 IODOD;
If Pro-22 parameter is DODTD , then device operates with offset. If SET1 is negative value, then Output-1 will be active in SET2-SET1. This option offers us to solve wrong cutting problem on the speedy mechanic, by reaching slowly to the target.

## (SET1=SET1 +SET2)

For example ;if SET1 $=-000100 ;$ SET2 $=000500$; then SET1 $=-100+500=400$

If more sensitivity is needed, Pro-Di parameter can be selected 0

For example, while x 1 phase shifting counting is performed in a system with a cutting unit as shown above, a 100-pulse encoder is connected to Ch-A and Ch-B inputs. If the system is advanced 100 cm for 50 encoder pulses, so it is advanced 2 cm with 1 encoder pulse.
When $x 2$ phase shifting counting is performed, for the system is being advanced $100 \mathrm{~cm}, 100$ encoder pulses are needed. In this case, the system is advanced 1 cm with 1 encoder pulse.

When x4 phase shifting counting is performed, for the system is being advanced $100 \mathrm{~cm}, 200$ encoder pulses are needed. In this case, the system is advanced 0.5 cm with 1 encoder pulse.

Sensitivity of the system is changed from 2 cm to 0.5 cm .

## EXAMPLE-5:

There are two sensors in Ch-A and Ch-B inputs for determining the amount of the liguid in Channel-A and Channel-B. Multiplication coefficient parameter Pro-3D is adjusted to converts the pulses to observe the amount of the liquid exactly in the actual value screen. (For example liter)
For observing total amount of liquid Pra-D must be

If the tank is filled with liguid 20 liters from
 Channel-1 and 40 liters from Channel-2, 60 liters is observed in actual value screen.

If Output-1 controls the Channel-1, Output-2 controls the Channel-2, SET1 is 20 and SET2 is 40, then it is possible to close the system after filling the tank with 20 liters from Channel-1 and 40 liters from Channel-2


7．6 BATCH COUNTER Parameters
SET1
SET value for Output－1．Control of the Output－1 is done according to this value．It can be adjusted from DODODS to 939398
SET
SET value for Output－2．Control of the Output－2 is done according to this value．It can be adjusted from DODNDO to 999998


000000
000001 000002

000003
000004
000005 000006 000007
Pro－04

## Input Types and Functions

Upcount on rising edge of input Ch－A（INC）
Downcount on rising edge of input Ch－A（DEC）
Upcount on rising edge of input Ch－A and downcount on rising edge of input Ch－B（INC／DEC）
Upcount on rising edge of input Ch－A and Ch－B（INC／INC）
Upcount on rising edge of Ch－A input when Ch－B is at 0 ，downcount on rising edge of Ch－A input when Ch－B is at 1．（UP／DOWN）
x1 phase shifting（for incremental encoders）
x2 phase shifting（for incremental encoders）
x4 phase shifting（for incremental encoders）

## Pulse Time of Ch－A and Ch－B Inputs

This parameter is used for not to evaluate the pulses if it is produced because of electrical noise or pulse time is less than the determined time．It can be adjusted from DODODO to DOD250

## ローロー ロ曰 Output Functions



Manual Reset．BATCH counting operation continues until manual reset input is active．
ODOD，Automatic Reset．BATCH counting operation continues until Batch count value reaches to SET1 value．When Batch count value is equal to SET1 value，Batch count value becomes zero（for $0 \Rightarrow P$ ）and device starts to count again．

When SET1 value is shown on the screen if MANUAL RESET is applied，batch count value，when SET2 value is shown on the screen if MANUAL RESET is applied，normal count value becomes zero．

In operation with Manual or Automatic Reset，at the end of the reset operation，if counting direction parameter $P_{r a} 19$ is 0 DODO $(0 \Rightarrow P)$ ，count value
 For both conditions（ $0 \Rightarrow P$ or $P \Rightarrow 0$ ），batch count value becomes $\triangle D D D O$
i）For details on parameters，refer to Section 8 （Program Parameters）．

## Pra－ 14 Operation Form of Output－1


OL二厶⺝ 1 Output－1 Normally energised

## $\square \Gamma \square-1 \square$ Operation Form of Output－2


ONOD， 1 Output－2 Normally energised

## $\square \Gamma \square-1 \square$ Output－1 Pulse Time

Energising time for Output－1．It can be adjusted from SDODOD to 059393 If it is $\triangle \triangle D D O D$ ，then it operates indefinitely．
$\square \square^{\square-17}$ Output－2 Pulse Time
Energising time for Output－2．It can be adjusted from DODNDO to 029393 If it is DOUD．
$\square \Gamma \square-1 马$ Selection of counting direction
ANADAS Upcount（ $0 \Rightarrow$ Preset ）
ODNDG 1 Downcount（Preset $\Rightarrow 0$ ）

## ローローコワ Point Position for display

BZAZAZ No point
OROAS 1 Between first and second digits
ODODOD Between second and third digits

DNOD，

## $\square \boldsymbol{\square}-\square$ I Saving Count Value（Power down back－up）

BNODAD Count value is saved power is off and restored on power up．

Pro－23 Slave Adress
Device address for serial communication bus．
It can be adjusted from DODAD to 082247
$\square \boldsymbol{\square} \boldsymbol{\square} \boldsymbol{\square}$－Selection of Modbus Protocol Type
OИODOD MODBUSASCII communication protocol is selected．
НПППП 1 MODBUS RTU communication protocol is selected
ローローコロ Parity
DANAOS No parity
OZAZA O Odd parity
BDロロロㄹ Even parity
i For details on parameters，refer to Section 8 （Program Parameters）．

## ローローム曰 Baud Rate

BNOCOC 1200 Baud Rate
OИOИИ 2400 Baud Rate
OИOU口2 4800 Baud Rate

ODOD， 19200 Baud Rate

## ローローム7 Stop Bit

OL二口丂口 1 Stop Bit
OИДИ二 2 Stop Bits
$\square \triangleright \square-\square \square$ Reset and Set protection（Accessing from front panel）
BALADS There is no Reset and Set protection

ODNDZ2 SET1 and SET2 protection is active
ODN二口3 Reset Button，SET1 and SET2 protection is active（Full protection）
ОДПППU SET1 protection is active
ODDDИ5 SET2 protection is active

## ローローヨワ Multiplication Coefficient

Count value is multiplied with this value．It can be adjusted from $0,0 \mathrm{DO}$ Ito． 999939 ．If it is iDOUD，it has no effect．

## $\square ゥ \square-\square \square$

## Program Password

It is used for accessing to the program parameters．
 password protection．

### 7.6.1 BATCH COUNTER Applications Examples

## EXAMPLE-1:

There is a production band like in diagram below. Bottles are perceived by a proximity sensor in Ch-A. If

$$
\text { Pro-Di }=\text { DODODD ; Pro-30 }=0 \text { iDODO ; }
$$



Device is used in a packing line as shown on the left. Bottles must be counted into packs of 4 bottles and dispatched in a box containing a batch of 4 packs. According to this, SET1 and SET2 are defined 4.4 pieces of packet which contain a batch of 4 series are allowed to be formed.
If Pro-05 = DODUD I(Automatic Reset1);after arranging the bottles in a box as shown on the left, output- 1 will be active and it stops the system. Batch count value is reset and it will be ready to count the new series.

## EXAMPLE-2:

There is a cloth workbench. An encoder with 100 pulse is connected to this system. The encoder is connected to Ch-A and Ch-B inputs.

$$
\begin{aligned}
& \text { Pro-19=00000 And Pro-30 = } 0 \text { IDODO; }
\end{aligned}
$$



Coefficient parameter is adjusted to be able to observe the cloth length in actual value screen. If we want to be cut the cloth in same lenght at 5 m and stopped the system when 40 pieces of 5 m cloths are formed, SET1 must be 40 and SET must be 5 .


7．7 TIMER Parameters
SET value for Output－1．Control of the Output－1 is done according to this value．It can be changed by time unit and scale selection parameter Pro－05
SET
SET value for Output－2．Control of the Output－2 is done according to this value．It can be changed by time unit and scale selection parameter Pro－05

## Pro－05

Time Unit and Scale Selection

It can be adjusted from 0202005 to 09359
Onज二口
Minute／Second
It can be adjusted from $\triangle 20205$ to 03939
OUOBD Second／Millisecond It can be adjusted from 0000．0 to 093939

OИNOИ3 Hour／Minute It can be adjusted from 000000 to 0023．53

ロПППП4 Hour It can be adjusted from 00020 to 093939

ONONO5 Minute It can be adjusted from 02020 to 093993

ONONOG Second It can be adjusted from 080200 to 093939

## Pro－05

Output Functions
000000
Manual Reset－1．Device continues to count till manual reset is applied． Output－2 pulse time $P_{r \sigma^{-}} 17$ is not considered．
जПNOT Manual Reset－2．Device continues to count till count value reaches to SET2 value．For starting to count again，manual reset input must be active．Output－ 2 pulse time Pra－17］is not considered．

000002
Manual Reset－3．It operates like Manual Reset－1．Only difference，output－2 pulse time Pro－17 is considered．

000003
Automatic Reset－1．Count value becomes zero $(0 \Rightarrow P)$ when it reaches to SET2 value．Count value is added to total count value and device starts to count from ODODOD
ODODU Automatic Reset－2．Counting is stopped when count value reaches to SET2 value．Count value is becomes zero $(0 \Rightarrow P)$ at the end of output－2 pulse time Pro－17 And device starts to count again．



For details on parameters，refer to Section 8 （Program Parameters）．

ODOD5 Automatic Reset－3．Count value becomes zero $(0 \Rightarrow P)$ when it reaches to SET2 value．Device starts to count again．Meanwhile，SET2 value is shown in actual value display，count value is shown at the end of output－2 pulse time Pra－17］

ODOD5 Automatic Reset－4．Counting is continued when count value reaches to SET2 value．Count value is becomes zero $(0 \Rightarrow P)$ at the end of Output－2 pulse time Pro－17．Device starts to count again．

SODA 7 Automatic Reset－5．When count value reaches to SET2 value，SET1 changes position，count value becomes zero（for $0 \Rightarrow P$ ）Output－1 and Output－ 2 does not change position position until count value reaches to SET2 value．



## Pro－14 <br> 000000 <br> GKG母G <br> Pro－15 <br> 

Operation form for Output－1
Output－1 Normally non－energised
Output－1 Normally energised

## $\square \Gamma \square-1 \square$ Operation form for Output－2 <br> DNODOU Output－2 Normally non－energised <br> ONO 1 Output－2 Normally energised

Output－1 Pulse Time
Energising time for Output－1．It can be adjusted from DODODO to 059393 If it is DODOD，it operates indefinitely．
Output－2 Pulse Time
 If it is SDCDED，it operates indefinitely．

## $\square\ulcorner\square-1 马$ Selection of counting direction


꾸꾸
Downcount（Preset $\Rightarrow 0$ ）


Saving Count Value（Power down back－up）
ODNO Count value is saved when power is off and restored on power up．
BONG 1 Count value is not saved to memory when power is off

## ローロームヨ Slave Address

Device address for serial communication bus． It can be adjusted from DODSD to 025247

## $\nabla_{r a-\beth}$ Selection of Modbus Protocol Type

ODODOD MODBUSASCII communication protocol is selected．
ODODC 1 MODBUS RTU communication protocol is selected

## Pro－25 Parity


OИOИन O Odd parity
NODO2 Even parity
ローローロ曰 Baud Rate
ONOUS 1200 Baud Rate
OИOИ〇 2400 Baud Rate
OAODO2 4800 Baud Rate

ODND， 19200 Baud Rate
ローローコ7 Stop Bit



## $\square \square \square-\square \square$ Reset and Set protection（Accessing from front panel）

ONODN There is no Reset and Set protection
ODOD二 I Reset Button protection is active
BNADAㄹ SET1 and SET2 protection is active
ODN二口3 Reset Button，SET1 and SET2 protection is active（Full protection）
ODOD，SU SET1 protection is active
ODNDE5 SET2 protection is active

## $\square \square \square-\square \square$

## Program Password

It is used for accessing to the program parameters． It can be adjusted from 020000 to 093993 ．If it is 800005 ，there is no password protection．

### 7.7.1 Timer Applications Examples

## EXAMPLE-1:

There is a switch for giving start and stop signal on PAUSE input.
If Pro-05 = OODOD ;


When switch is "On", counting is started (Minute / second). When switch is "Off", counting is stopped. Time between opening and closing of the switch is observed on actual value screen.
Expired time can be reset with manual reset. If total operation time is wanted to be observed on the screen, manual reset is not applied and after Start/Stop operation counting is started from the last count value.

NOTE: If output-1 and output-2 is wanted to be used as an alarm output;
For example SET1 $=10.00$; SET2= 30.00 and Pro-D5 $=\square O D D 22$
Device starts to count (Minute / second) when switch is "On". It is possible to have a warning when SET1 and SET2 times are expired and stopping the alarm at the end of the Output-1 and Output-2 pulse times.( Pro-15 And Pro-17 )


7．8 FREQUENCYMETER／TACHOMETER Parameters
SET value for Output－1．Control of the Output－1 is done according to this value．It can be adjusted from 0 939398

SET value for Output－2．Control of the Output－2 is done according to this value．It can be adjusted from DODNDD to 999398

## $\square ゥ \square-\square \exists$ Selection of Measurement Method

DNODN Frequency or cycle is calculated by measuring cycle time of the signals in Ch－ Ainput
DИOD 1 Frequency or cycle is calculated by counting the pulses in Ch－A input during the time is set in measurement period parameter Pra－\＃B

## Pro－04

Pulse Time of Ch－A and Ch－B Inputs
It is used not to evaluate the false signals by electrical noise or the signal that is less than the determined pulse time．
It can be adjusted from 820200 to 020250 msec

## $\square \square \square-\square 7$ Time Out（Input Signal Reset Time）

The actual value is reset，if there is no signal in Ch－A input during this time


## Pro－08 <br> Measurement Period <br> Number of pulses is counted during this time <br> 

## $\square$ ロロ－$\square$ Output－1 Function

ONODT Output－1 is latched．It does not change position until manual reset is applied．

OИOИ 1 Non－latched with hysteresis output is selected．

Output－1 is an alarm output．For details，refer to Output－1 Alarm functions parameter Pro－11．

## $\square \square_{\square}-1 \square$ Output－2 Function

ODOD Output－2 is latched．It does not change position until manual reset is applied．

OAOA．Non－latched with hysteresis output is selected．

## Pro－11 <br> Alarm Functions for Output－1

 becomes active according to this parameter
ODODOS High Alarm．
ADD 1 Low Alarm．
ODDDD2 Deviation High Alarm．



## ローロー In

Hysteresis for Output－1
Hysteresis for Output－1．It is used if Output－1 is non－latched．
It can be adjusted from 080000 to 050000

## Pro－ 13

Hysteresis for Output－2
Hysteresis for Output－2．It is used if Output－2 is non－latched．
It can be adjusted from 000000 to 050000

## $\square_{\Gamma ロ-14}$ Operation form for Output－1

ODODOD Output－1 Normally non－energised
OИON二 1 Output－1 Normally energised

## $\square ゥ \square-15$ Operation form for Output－2

BNODSत Output－2 Normally non－energised
OДО二厶 1 Output－2 Normally energised

## ローロー $1 \square$ <br> Output－1 Pulse Time

Energising time for Output－1．It can be adjusted from 0 ODODO to 009393 If it is DODSDS ，then it operates indefinitely．


Output－2 Pulse Time



## Pro－18 <br> Start of Controlling

DODOU Controlling is started when the device is energised
DNOD二 Controlling is started when count value reaches to SET1 value．
OИODO2 Controlling is started when count value reaches to SET2 value．

## ローローコワ Point Position for display

ONO二口马 Nopoint
OROAD 1 Between first and second digits
OHODOD Between second and third digits
BDODZ3 Between third and fourth digits
O，O， 4 Between fourth and fifth digits

## ローロームヨ Slave Address

Device address for serial communication bus．
It can be adjusted from DODND to 020247
$\square \square \square ー \square$ Selection of Modbus Protocol Type
DNODOD MODBUSASCII communication protocol is selected．
ADADA 1 MODBUS RTU communication protocol is selected

## Pro－25 Parity

ロロロロロロ No parity
OASAS O Odd parity
ODDDD2 Even parity

## ローローム曰 Baud Rate

DODODS 1200 Baud Rate
OROD二 2400 Baud Rate
근ㄱㄹ 4800 Baud Rate
ODN二口3 9600 Baud Rate

ローローコ7 Stop Bit

OAOAS 2 Stop Bits
i For details on parameters，refer to Section 8 （Program Parameters）．

## $\square\ulcorner\square-\square \square$ Reset and Set protection（Accessing from front panel）

므는 There is no Reset and Set protection
คロロロ二 i Reset Button protection is active
ODNDE2 SET1 and SET2 protection is active
ODN二〇3 Reset Button，SET1 and SET2 protection is active（Full protection）
ODOD，SET1 protection is active
ODNDИ5 SET2 protection is active

## $\square ー \square-\beth 马$ Frequency／Cycle Multiplication Coefficient

Count value is multiplied with this value．It can be adjusted from $\triangle D O D E$ to 009993

## ローローヨワ Multiplication Coefficient

Count value is multiplied with this value．It can be adjusted from 0 DDO Ito． 999993 ．If it is IUDOU，it has no effect．
$\square$ ロロ－ロム Program Password
It is used for accessing to the program parameters．
It can be adjusted from 000005 to 099993 ．If it is 000000 ，there is no password protection．

### 7.8.1 FREQUENCYMETER / TACHOMETER Applications Examples

Two different methods are used in Frequencymeter / Tachometer function;
Method-1: To get frequency or cycle value by measuring the revolution time (This method is used if the sensor sends one pulse per revolution)
Method -2 : To get frequency or cycle value by counting the pulses during the time is set in Pro-DB parameter

## Method-1 :

If Pro-03 is 0 ODODO ;
Measuring starts on rising edge of Ch-Ainput. Time (T) is between two rising edge.


If Pro-23 parameter is PODOD , Pro-30 parameter is 0 IDODO , then speed is measured cycle per second.
For measuring the speed cycle per minute, Pra-29 parameter must be DODE5D
For measuring the speed cycle per hour, Pro-29 parameter must be 023500

## EXAMPLE-1:

There is a cloth workbench as shown below:
When Pro-29 parameter is DODDD , Pra-30 parameter is IDODO, cloth is advanced 80 cm per revolution and $20 \mathrm{cycle} / \mathrm{sec}$ is observed on the display.
User can observe cloth length, 80 cm , on the display by changing the Pro-29 and Pro-30 Parameter


Pro-30 $=\frac{\text { Cloth Length in one revolution }}{\text { Pro- } 29]^{*} \text { Value on the display ( } \mathrm{f} \text { ) }}$
If Pro-23 $=1$
Pro-3D Multiplication coefficient $=80 / 20=4$
After adjustment of the parameter, $80 \mathrm{~cm} / \mathrm{sec}$ is observed on the display.

For dm/sec, point position for display parameter Pra-2D must be 0 ODED
For $\mathrm{m} / \mathrm{sec}$, point position for display parameter Pro-20 must be 0
Forcm/minute, Pro-29 parameter must be DODS50
Forcm/hour, Pro-29 parameter must be 0.3500

## Method-2:

If Pro-03 parameter is ODODO
Pulses in Ch-A input is counted during time is set in Pro-DG parameter. Average time for one pulse is calculated.


## EXAMPLE-2:

For one revolution of cylinder 10 pulse is applied in Ch-A input during Pro-0B = DODOZ.


If 10 pulse is applied during 2 secs;
$T=2 / 10=0.2 \sec f=1 / T f=5 \mathrm{cycle} / \mathrm{sec}$ is shown on the display

If Pro-29 parameter is PDOD 5 and Pro-30 parameter is 0 IDODD , speed is measured as cycle per second.
For cycle / minute, Pro-2马parameter must be 000050
For cycle/ hour, Pro-29parameter must be 003500


## EXAMPLE-3:

 If Pro-29 parameter is BODED I and Pro-30 Parameter is IDOD, speed of the system (cycle per second) is calculated as shown below:

If 8 pulse is applied during 0.5 sec ;
$T=0.5 / 8=0.0625 \mathrm{sec} f=1 / T \mathrm{f}=16 \mathrm{cycle} / \mathrm{sec}$ is shown on the display
For cycle/minute, Pro-29 parameter must be DODE5S
For cycle/hour, Pro-29 parameter must be 003500


7．9 CHRONOMETER Parameters
SET1
SET value for Output－1．Control of the Output－1 is done according to this value．It can be changed by time unit and scale selection parameter Pro－～5
SET2
SET value for Output－2．Control of the Output－2 is done according to this value．It can be changed by time unit and scale selection parameter Pro－05

## Pro－02

Input Type and Function Selection for Chronometer
OИODND Period measurement of signals in Ch－A input
ODOD二 1 Pulse time measurement of signals in Ch－A input
ODOD二ㄹ Sum of the time difference between Ch－A and Ch－B inputs rising edges

## Pro－04

Pulse Time of Ch－A and Ch－B Inputs
It is used not to evaluate the false signals by electrical noise or the signal that is less than the determined pulse time．
It can be adjusted from ODODOD to 020250 msec

## $\square ゥ \square-\square \square$ Time Unit and Scale Selection

BNONAZ
Hour／Minute

BNOAD

B～ロロロㄹ
／Milisecond
It can be adjusted from 0000．00 to 0.3939
OИO～O3 Hour／Minute
It can be adjusted from 000205 to 022359
ODODC4 Hour
It can be adjusted from 0000.0 D to 099993
000005 Minute
It can be adjusted from 02020515939
ONOUNG Second
It can be adjusted from 0802003

## $\square$ ロローワ曰 Output Functions



Manual Reset－1．Device continues to count till manual reset is applied． Output－2 pulse time Pro－17］is not considered．

In operation with Manual or Automatic Reset，at the end of the reset operation，if



For details on parameters，refer to Section 8 （Program Parameters）．

ODOD 1 Manual Reset－2．Device continues to count till count value reaches to SET2 value．For starting to count again，manual reset input must be active．Output－ 2 pulse time $P_{r a-17}$ is not considered．
ODODOD Manual Reset－3．It operates like Manual Reset－1．Only difference，output－2 pulse time Pro－17 is considered．
ORODJ Automatic Reset－1．Count value becomes zero（for $0 \Rightarrow P$ ）when it reaches to SET2 value and device starts to count again．

OПOD，Automatic Reset－2．Counting is stopped when count value reaches to SET2 value．Count value becomes zero（for $0 \Rightarrow P$ ）at the end of output－2 pulse time Pro－17］And device starts to count again．

ODOD5 Automatic Reset－3．Count value becomes zero（for $0 \Rightarrow P$ ）when it reaches to SET2 value．Device starts to count again．Meanwhile，SET2 value is shown in actual value display，count value is shown at the end of output－2 pulse time．
ONODN5 Automatic Reset－4．Counting is continued when count value reaches to SET2 value．Count value becomes zero $(0 \Rightarrow P)$ at the end of Output－2 pulse time［Pro－17］device starts to count again．
ดИПИП 7 Automatic Reset－5．When count value reaches to SET2 value，SET1 changes position，count value becomes zero（ $0 \Rightarrow \mathrm{P}$ ）．Output－1 and Output－2 do not change position，until count value reaches to SET2 value．

In operation with Manual or Automatic Reset，at the end of the reset operation，if counting direction parameter Pra－19 is DODDOD（ $0 \Rightarrow P$ ），count value


## $\square ー ロ-1$ Operation form for Output－1

BRODSD Output－1 Normally non－energised
OДО二， 1 Output－1 Normally energised
$\square$ ロロー 15 Operation form for Output－2
BNODSO Output－2 Normally non－energised
OИODИ 1 Output -2 Normally energised


Energising time for Output－1．It can be adjusted from 000000 to 0.5939 If it is ODODOD ，then it operates indefinitely．


Output－2 Pulse Time
Energising time for Output－2．It can be adjusted from ODODOD to 059939 If it is DODSO


OLOM I Downcount（Preset $\Rightarrow 0$ ）
i For details on parameters，refer to Section 8 （Program Parameters）．

##  <br>  power up．

ODODS 1 Count value is not saved to memory when power is disconnected

## Pro－23

Slave Address
Device address for serial communication bus． It can be adjusted from DODSD to 025247
Pro－24
000000
Selection of Modbus Protocol Type
$00000:$
MODBUS ASCII communication protocol is selected．
MODBUS RTU communication protocol is selected
Pro－25 Parity
AODNOS No parity

BNODD2 Even parity
ローローム曰 Baud Rate
OUNOU 1200 Baud Rate
OИOПИ 2400 Baud Rate
OИODO2 4800 Baud Rate


ローローコ

ロПППИ i 2 Stop Bits
Pro－2B
DNODS There is no Reset and Set protection
ANOAS I Reset Button protection is active
ODOLD2 SET1 and SET2 protection is active
ODODZ3 ResetButton，SET1 and SET2 protection is active（Full protection）
OD，二与 4 SET1 protection is active
ODNOS5 SET2 protection is active
$\square$ ロロ－－■
Program Password
It is used for accessing to the program parameters．
 password protection．
i）For details on parameters，refer to Section 8 （Program Parameters）．

### 7.9.1 Examples About CHRONOMETER Applications

## EXAMPLE-1:

There is a switch for giving start and stop signal on Ch-Ainput.



When switch is "On", counting is started (Minute / second). When switch is "Off", counting is stopped. Time between opening and closing of the switch is observed on actual value screen.
Expired time can be reset with manual reset. If total operation time is wanted to be observed on the screen, manual reset is not applied and after Start/Stop operation counting is started from the last count value.

## EXAMPLE-2:

There is a production band as shown below. There are two sensors, first is on Ch-A input used for starting the system, second is on Ch-B input used for stopping the system. If



When the object passes in front of the first sensor on Ch-A input, counting is started (Minute / second).
When the object passes in front of the second sensor on Ch$B$ input, counting is stopped.
Time between two objects can be determined.

### 7.10 Accessing to the Program Parameters

Parameters are grouped as program parameters. Accessing to the program parameters is same for all functions. So, only accessing to the program parameters for COUNTER / "TOTALIZER COUNTER" is explained in this section. For details on parameters refer to PROGRAM

The most significant digit of the parameter (3rd digit for this parameter) flashes.

Press PROG button to exit from programming section without doing any changes.


PARAMETERS section.


Operation
Screen


When PROG button is pressed, password must be entered for accesing to the parameters.


You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER
Screen


Password Screen

The most significant digit of the parameter (4th digit for this parameter) flashes.

Enter password with shift and increment button.


Press Enter button to confirm password


Press ENTER button
 button.


The most significant digit of the parameter (1st digit for this parameter) flashes.


Press PROG button to exit from programming section without doing any changes.

The most significant digit of the parameter (1st digit for this parameter) flashes.


The most significant digit of the parameter (4th digit for this parameter) flashes.
Press PROG button to exit from programming section without doing any changes.


Press PROG button to exit from programming section without doing any changes.

## Output Functions

You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER button.

Press ENTER button

## Output-1 Operation Form

You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER button.

Press ENTER button

## Output-2 Operation Form

You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER button.

Press ENTER button

## Output-1 Pulse Time

You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER button.

Press ENTER button

The most significant digit of the parameter (4th digit for this parameter) flashes.
$\square$


Press PROG button to exit from programming section without doing any changes.

The most significant digit of the parameter (1st digit for this parameter) flashes.


The most significant digit of the parameter (1st digit for this parameter) flashes.


Press PROG button to exit from programming section without doing any changes.


Press PROG button to exit from programming section without doing any changes.


The most significant digit of the parameter (1st digit for this parameter) flashes.


Press PROG button to exit from programming section without doing any changes.


## Output-2 Pulse Time

You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER button.

Press ENTER button

## Direction of the Counting

You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER button.

Press ENTER button

## Point position for the display

You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER button.

Press ENTER button

## Saving Count Value (Power down back-up)

You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER button.

Press ENTER button

The most significant digit of the parameter (1st digit for this parameter) flashes.


Press PROG button to exit from programming section without doing any changes.

The most significant digit of the parameter (3rd digit for this parameter) flashes.

Press PROG button to exit from programming section without doing any changes.

The most significant digit of the parameter (1st digit for this parameter) flashes.


The most significant digit of the parameter (1st digit for this parameter) flashes.


Press PROG button to exit from programming section without doing any changes.


Press ENTER button

## Parity Selection

You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER button.

Press ENTER button

The most significant digit of the parameter (1st digit for this parameter) flashes.
$\downarrow$
Press PROG button to exit from programming section without doing any changes.

The most significant digit of the parameter (1st digit for this parameter) flashes.


The most significant digit of the parameter (1st digit for this parameter) flashes.


Press PROG button to exit from programming section without doing any changes.
有


Press PROG button to exit from programming section without doing any changes.


The most significant digit of the parameter (6th digit for this parameter) flashes.


Press PROG button to exit from programming section without doing any changes.


## Baud Rate

You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER button.

Press ENTER button

## Stop Bit Selection

You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER button.

Press ENTER button

## Reset and Set Protection

You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER button.

Press ENTER button

## Multiplication Coefficient

You can change the parameter with INCREMENT button, save it to the memory and pass to the next parameter with ENTER button.

Press ENTER button


# $\square-\square-\Gamma$ Input Types and Functions <br> (It is accessible in COUNTER / "TOTALIZER COUNTER" and BATCH COUNTER functions) 






## 무~ロコ

Upcount on rising edge of Ch-A input.
Downcount on rising edge of Ch-B input.


## 000003 <br> Upcount on rising edge of Ch-A input Upcount on rising edge of Ch-B input



## ППППワ4 Upcount on rising edge of Ch-A input when Ch-B is at 0 Downcount on rising edge of $\mathrm{Ch}-\mathrm{A}$ when $\mathrm{Ch}-\mathrm{B}$ is at 1



## <compat>ᄀ<compat>ᆱППム xi Phase Shifting (for incremental encoders) <br> Upcount on rising edge of Ch-A input when Ch-B is at 0 Downcount on falling edge of Ch-Ainput when Ch-B is at 0



If ProD is 000005, Pro-04 must be 000000 .If not counting is not performed.

Downcount on rising edge of $\mathrm{Ch}-\mathrm{A}$ when $\mathrm{Ch}-\mathrm{B}$ is at 1 Upcount on falling edge of $\mathrm{Ch}-\mathrm{A}$ when $\mathrm{Ch}-\mathrm{B}$ is at 1




## 050507

x4 Phase Shifting (for incremental encoders)
Upcount on rising edge of Ch-A when Ch-B is at 0 Downcount on falling edge of $\mathrm{Ch}-\mathrm{A}$ when $\mathrm{Ch}-\mathrm{B}$ is at 0 Downcount on rising edge of Ch-A when Ch-B is at 1 Upcount on falling edge of Ch-A when Ch-Bis at 1

Downcount on rising edge of $\mathrm{Ch}-\mathrm{B}$ when $\mathrm{Ch}-\mathrm{A}$ is at 0 Upcount on falling edge of $\mathrm{Ch}-\mathrm{B}$ when $\mathrm{Ch}-\mathrm{A}$ is at 0 Upcount on rising edge of Ch-B when Ch-A is at 1 Downcount on falling edge of $\mathrm{Ch}-\mathrm{B}$ when $\mathrm{Ch}-\mathrm{A}$ is at 1


ПППППП Period measurement in Ch－Ainput．



Selection of Measuring Method (It is accessible only in FREQUENCYMETER / TACHOMETER Function)

Frequency or cycle is calculated by measuring cycle time of the signals in Ch-Ainput


Frequency or cycle is calculated by counting the pulses in Ch-A input during the time is set in measurement period parameter Pro-0B

For details on these methods, refer to Section 7.8.1"Examples About Frequencymeter/Tachometer Function Applications"
Only Ch-A input performs in Frequencymeter / Tachometer function.

## Pro-04

Pulse Time of Ch-A and Ch-B Input
(It is accessible in functions except for TIMER function)
It determines the pulse time of Ch-A and Ch-B inputs.It is used not to evaluate the false signals by electrical noise or the signal that is less than the determined pulse time.

If it is $\triangle D O D O$, there is no time protection in Ch-A and Ch-B inputs to prevent the false signals. If Input Types and Functions parameter Pro-Di is DODED5, DODO 7 then pulse time of $\mathrm{Ch}-\mathrm{A}$ and Ch -B parameter Pro- 14 must be DTOUDT. If not counting is not performed.

## $\square-\square \square$ Selection of Time Unit and Scale <br> (It is accessible in TIMER and CHRONOMETER functions)



Hour / Minute
It can be adjusted from 020.05 to 03959


Minute / Second
It can be adjusted from 0002.50 to 03935


Second / Millisecond
It can be adjusted from 000000 to 09993


Hour / Minute
It can be adjusted from 0000.00 to 0023.53

##  <br> 

## 

Second
It can be adjusted from $\boxed{\square N O D G}$ to 099999
After adjustment of Time Range parameter Pra-D5, if SET1 and SET2 values are not appropriate for this selection, SET1 and SET2 are changed according to this selection.(E.g. If time range is 99.99 and SET1 is 45.94 , there is no problem. If time range is 99.59 and SET1 is 45.94 , then SET1 is changed as 45.59 )

## $\square-\square-\Gamma \quad$ Output Functions <br> (It is accessible in functions except for FREQUENCYMETER / TACHOMETER function) <br> This parameter can be adjusted from 20000 D to 20001 in Batch Counter function and operates different from the other functions.

Device continues to count till manual reset is applied. Output-2 pulse time $P_{\Gamma a^{-1}} 7$ is not considered.

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER function is explained below:

Counting direction : $\mathbf{0} \Rightarrow \mathbf{P}$ (Upcount) Pro-19 $=0$ DOD


When count value reaches to SET1 value, Output-1 becomes active. If
 condition until manual reset input is active. If Output-1 pulse time
Pro-16 Is not 0, at the end of the pulse time Output-1 becomes inactive. When count value reaches to SET2 value, Output-2 becomes active. Counting continues over SET2 value. Output-2 pulse time Pra-17 Is not considered.

Count value is added to total count value when manual reset is active in COUNTER/"TOTALIZER COUNTER" functions.

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functions is explained below:

Counting direction : $\mathbf{P} \Rightarrow \mathbf{0}$ (Downcount) Pro-19 $=$ DNDED


When the count value reaches to SET1 value, Output-1 becomes active. If Output-1 Pulse Time Pra-15 is DODODD, Output-1 does not change condition until manual reset input is active. If Output-1 pulse time Pro-15 is not 0, Output-1 becomes inactive at the end of the pulse time. When actual value reaches to DODODS, Output-2 becomes active. Counting countinues under ODODOD Output-2 pulse time Pra-17 Is not considered.

Count value is added to total count value when manual reset is active in COUNTER / "TOTALIZER COUNTER" functions.

## Pro-06=00000 |

## Manual Reset-2.

(Output-2 Pulse Time Pro-17 is not considered)

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functions is explained below:

Counting direction : $\mathbf{0} \Rightarrow \mathbf{P}$ (Upcount) Pro-19 $=00000$


When the count value reaches to SET1 value, Output-1 becomes active. If Output-1 pulse time Pro- I6] is DODODS , Output-1 does not change position until manual reset input is active. If Output-1 pulse time Pro-15 is not 0 , Output- 1 becomes inactive at the end of the pulse time.
When the count value reaches to SET2 value, Output-2 becomes active. Counting does not continue over SET2 value. For starting to count manual reset input must be active. Output-2 Pulse Time Pro-17] Is not considered.
Count value is added to total count value when manual reset is active in COUNTER/"TOTALIZER COUNTER" functions.

## How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functions is explained below:




When the count value reaches to SET1 value, Output-1 becomes active. If Output-1 pulse time Pro-15 is DODODD, Output-1 does not change condition until manual reset input is active. If Output-1 pulse time $\mathrm{Pra}_{\mathrm{o}} \mathrm{I}[\mathrm{]}$ is not 0 , Output- 1 becomes inactive at the end of the pulse time.
When the count value reaches to 020005 value, Output-2 becomes active. Counting does not continue under $\triangle$ ODODO . For starting to count manual reset input must be active. Output-2 pulse time Pro-17 Is not considered.

Count value is added to total count value when manual reset is active in COUNTER/"TOTALIZER COUNTER" functions.

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functions is explained below:

Counting direction : $\mathbf{0} \Rightarrow P$ (Upcount)
Pro-19 = OnODNG


When the count value reaches to SET1 value, Output-1 becomes active. If Output-1 Pulse Time Pro-15 is not 0 , Output-1 changes position at the end of the pulse time.If Output-1 Pulse Time Pro-15 is BNODODt changes position until Manual Reset input is active or according to Output-2.
When the count value reaches to SET2 value, Output-2 becomes active. Counting continues until manual reset input is active. If Output-2 Pulse Time $\operatorname{Pra}-17$ is not 0 , Output-2 changes position at the end of the pulse time. In this case, if Output-1 is active, it becomes inactive with Output-2.

Count value is added to total count value when manual reset is active in COUNTER / "TOTALIZER COUNTER" functions.

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER function is explained below:

Counting direction : $\mathbf{P} \Rightarrow \mathbf{0}$ (Downcount) Pro-19 $=0000$


When the count value reaches to SET1 value, Output-1 becomes active. If Output-1 pulse time $\operatorname{Pr} \mathrm{P}^{-16}$ is not 0 , Output-1 changes position at the end of the pulse time.If Output-1 Pulse Time Pro- ib is 0 it changes position until Manual Reset input is active or according to Output-2.
When count value reaches to $\triangle \operatorname{DODOD}$ value, Output-2 becomes active. Counting continues until manual reset input is active. If Output-2 Pulse time $\operatorname{Pro-17}$ is not 0 , Output-2 changes position at the end of the pulse time. In this case, if Output-1 is active, it becomes inactive with Output-2.

Count value is added to total count value when manual reset is active in COUNTER / "TOTALIZER COUNTER" functions.

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functions is explained below:

Counting direction : $0 \Rightarrow P$ (Upcount)
Pro-19 $=000000$


When the count value reaches to SET1 value, Output-1 becomes active. If Output-1 pulse time Pra-15 is not 0, Output-1 changes position at the end of the pulse time.If Output-1 Pulse Time Pro-15 is $\operatorname{PODODO}$, it changes position until Manual Reset input is active or according to Output-2 position.
When the count value reaches to SET2 value, Output-2 becomes active. Count value is reset. If Output-2 pulse time Pro-17 is not 0 , Output-2 changes position at the end of the pulse time. In this case, if Output-1 is active, it becomes inactive with Output-2.

Count value is added to total count value when automatic reset is active in COUNTER / "TOTALIZER COUNTER" functions.

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER function is explained below:

Counting Direction : $\mathbf{P} \Rightarrow \mathbf{0}$ (Downcount) Pro-13 $=$ DNDDS


When the count value reaches to SET1 value, Output-1 becomes active. If Output-1 pulse time Pro-15 is not 0 , Output-1 changes position at the end of the pulse time.If Output-1 Pulse Time Pro- $^{15}$ is 000005 it changes position until Manual Reset input is active or according to Output-2 position.
When the count value reaches to $D 2050 \mathrm{D}$ value, Output-2 becomes active. Count value becomes equal to Set-2 value and counting is started again. If Output-2 pulse time Pra-17 is not 0, Output-2 changes position at the end of the pulse time. In this case, if Output-1 is active, it becomes inactive with Output-2.

Count value is added to total count value when automatic reset is active in COUNTER / "TOTALIZER COUNTER" functions.

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER function is explained below:

Counting direction : $\mathbf{0} \Rightarrow \mathbf{P}$ (Upcount) Pro-19 $=$ BLOOD


When the count value reaches to SET1, Output-1 becomes active. If Output-1 pulse time Pra-15 is not 0 , Output-1 changes position at the end of the pulse time. If Output-1 Pulse Time Pro- I6 is DODOD, it changes position until Manual Reset input is active or according to Output-2 position.
When the count value reaches to SET2, Output-2 becomes active. Counting is stopped. If Output-2 pulse time Pro-17 is not 0 , count value is reset and Output-2 becomes inactive at the end of the pulse time. In this case, if Output-1 is active, it becomes inactive with Output-2.

Count value is added to total count value when automatic reset is active in COUNTER / "TOTALIZER COUNTER" functions. not, Automatic Reset is not realised.

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functions are explained below:

Counting direction : $\mathbf{P} \Rightarrow \mathbf{0}$ (Downcount) Pro-19 $=0$ ODO


When the count value reaches to SET1, Output-1 becomes active. If Output-1 pulse time Pro-15 is not 0 , Output-1 changes position at the end of the pulse time. If Output-1 Pulse Time Pro- I6 is changes position until Manual Reset input is active or according to Output-2 position.
When the count value reaches to ODODO value, Output-2 becomes active. Counting is stopped. If Output-2 pulse time Pro-17 is not 0 , count value becomes equal to SET2 value, counting is started again and Output-2 becomes inactive. In this case, if Output-1 is active, it becomes inactive with Output-2.

Count value is added to total count value when automatic reset is active in COUNTER /" TOTALIZER COUNTER" functions. not, Automatic Reset is not realised.

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functions are explained below:


When the count value reaches to SET1, Output-1 becomes active.If Output-1 pulse time Pro-16 is not 0, Output-1 changes position at the end of the pulse time. If Output-1 Pulse Time Pra-15 is 800005 , it changes position until Manual Reset input is active or according to Output-2 position.
When the count value reaches to SET2, Output-2 becomes active and count value is reset.
When the count value reaches to SET2, Output-2 becomes active and count value is reset. But SET2 value is observed in actual value display. If Output-2 pulse time $P r_{\square-17}$ is not 0 , count value is observed in actual value display and Output-2 becomes inactive. In this case, if Output-1 is active, it becomes inactive with Output-2.
Count value is added to total count value when automatic reset is active in COUNTER / "TOTALIZER COUNTER" functions. not, Automatic Reset is not realised.

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functiona are explained below:

Counting Direction : $\mathbf{P} \Rightarrow \mathbf{0}$ (Downcount) Pro-19 = DNOD


When the count value reaches to SET1, Output-1 becomes active. If Output-1 pulse time Pro- $^{15}$ is not 0 , Output- 1 changes position at the end of the pulse time. If Output-1 Pulse Time Pro- I6 is DODODS, it changes position until Manual Reset input is active or according to Output-2 position.
When the count value reaches to $\triangle \mathcal{O D O D}$ value, Output-2 becomes active, count value becomes equal to SET2and counting continues. But ODODODobserved in actual value display. If Output-2 pulse time
Pro-17 Is not 0 , count value is observed in actual value screen and Output-2 becomes inactive at the end of the pulse time. In this case, if Output-1 is active, it becomes inactive with Output-2.

Count value is added to total count value when automatic reset is active in COUNTER /" TOTALIZER COUNTER" functions. not, Automatic Reset is not realised.

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functions are explained below:

Counting direction : $\mathbf{0} \Rightarrow \mathbf{P}$ (Upcount) Pro-19 $=0000 \mathrm{D}$


When the count value reaches to SET1, Output-1 becomes active. If Output-1 pulse time Pro- I6 is not 0 , Output- 1 changes position at the end of the pulse time. If Output-1 Pulse Time Pro-15 is 8 PDODO , it changes position until Manual Reset input is active or according to Output-2 position.
When the count value reaches to SET2, Output-2 becomes active and counting continues over 0 . If Output-2 pulse time Pro-17 is not 0 , count value is reset and Output-2 becomes inactive at the end of the pulse time. In this case, if Output-1 is active, it becomes inactive with Output-2.

Count value is added to total count value when automatic reset is active in COUNTER / "TOTALIZER COUNTER" functions. not, Automatic Reset is not realised.

How it operates in COUNTER / "TOTALIZER COUNTER", TIMER and CHRONOMETER functions are explained below:

Counting Direction : $\mathbf{P} \Rightarrow \mathbf{0}$ (Downcount) Pro-19 = OUDOL


When the count value reaches to SET1, Output-1 becomes active. If Output-1 pulse time Pro-15 is not 0, Output-1 changes position at the end of the pulse time.If Output-1 Pulse Time Pro-15 is DODSDC , it changes position until Manual Reset input is active or according to Output-2 position.
When count value reaches to 0 and counting continues under 0 . If Output-2 pulse Pro-17 time is not 0 , count value becomes equal to SET2 and Output-2 becomes inactive. In this case, if Output-1 is active, it becomes inactive with Output-2.

Count value is added to total count value when automatic reset is active in COUNTER / "TOTALIZER COUNTER" functions. not, Automatic Reset is not realised.

How it operates in COUNTER / "TOTALIZER COUNTER" functions are explained below:

Counting direction : $0 \Rightarrow P$ (Upcount) Pro-19 = 000000


If count value is equal or greater than SET1 value, then Output-1 becomes active. Output-1 pulse time $\mathrm{Pra-ib}_{\text {- }}$ is not considered.
If count value is equal or greater than SET2 value, then Output-2 becomes active. If count value is less than SET2 value, Output-2 becomes inactive. Output-2 pulse time $P_{r ロ^{-1}} 17$ is not considered.

Count value is added to total count value when Manual Reset is performed.

Counting direction : $\mathbf{P} \Rightarrow \mathbf{0}$ (Downcount) Pra-19 $=$ OLDOD


If count value is equal or less than SET1 value, then Output-1 becomes active. If it is greater than SET1 value, Output-1 becomes inactive. Output-1 pulse time $\left.\mathrm{Pra}^{-15}\right]$ is not considered.
If count value is equal or less than ODODOD value, then Output-2 becomes active. If count value is greater than ODODOD value, then Output-2 becomes inactive. Output-2 pulse time Pro-17 is not considered.
Count value is added to total count value when Manual Reset is performed.
i. It is preferred if upcount and downcount is performed at the same time.

How it operates in TIMER and CHRONOMETER functions are explained below:
Counting direction : $\mathbf{0} \Rightarrow P$ (Upcount)
Pra-13 $=$ BODNOS


Pra-16 $\neq 000000$ Pra-16 $=000000$ Pra-17] $\neq 000000$ or
Pra-17 $=000000$

If count value is equal to or greater than SET1 value, then Output-1 becomes active. If Output-1 pulse time Pro-I活 is not 0, Output-1 changes position at the end of the pulse time. If Output-1 pulse time Pro-16 Is DODOD, then Output-1 becomes inactive when count value reaches to SET2 value.
When count value reaches to SET2 value, count value is reset and Output-2 becomes active. Output-2 does not change position until count value reaches to SET2 value again.
Output-2 pulse time $\operatorname{Pro-17}$ is not considered.

Counting direction : $\mathbf{P} \Rightarrow \mathbf{0}$ (Downcount) $\quad$ Pro- $19=00001$


If count value is equal to or less than SET1 value, then Output-1 becomes active. If Output-1 pulse time $P_{r \sigma^{-}} 15$ is not 0 , Output-1 changes position at th end of the pulse time. If Output-1 pulse time
Pro-15 Is ODODOD, when count value reaches to DODODO , Output-1 becomes inactive.
When count value reaches to $\triangle 2050 \mathrm{D}$, count value becomes equal to SET2 value and Output-2 becomes active. Output-2 does not change position until count value reaches to 0 ODOD again. Output-2 pulse time Pro-17] Is not considered.

## $\square \square \square-\Gamma$ Output Functions for BATCH COUNTER

## 

How it operates in BATCH COUNTER function is explained below:
Counting direction : $\mathbf{0} \Rightarrow \mathrm{P}$ (Counting to upwards)
Pro-19 $=000000$


When count value reaches to SET2 value, count value is reset and Output-2 becomes active.If Output-2 pulse time Pro- 17 is 0 DOUD Then Output-2 does not change position until manual reset input is active. If Output-2 pulse time $\mathrm{Pr} \mathrm{Pa}^{-17}$ is not 0 , Output-2 becomes inactive at the end of the pulse time.
When Output-2 becomes active, batch count value is added 1(Batch count value can be observed by pressing SET1 button). When number of how many times Output-2 is active becomes equal to SET-1 value, then Output-1 becomes active. If Output-1 pulse time $\operatorname{Pro-15}$ is 0 ODOD , then Output-1 does not change position until manual reset input is active. If Output-1 pulse time Pro-i6 is not, then Output-1 becomes inactive at the end of the pulse time.

How it operates in BATCH COUNTER function is explained below:
Counting Direction : $\mathrm{P} \Rightarrow \mathbf{0}$ (Downcount)
Pra-19 $=00000:$


When count value reaches to $\triangle$ DODOD, count value becomes equal to SET2 and Output-2 becomes active. If Output-2 Pulse Time Pro- 17 is ODODOD , then Output-2 does not change position until manual reset input is active. If Output-2 pulse time Pro-17 is not 0 , then Output-2 becomes inactive at the end of the pulse time.
When Output-2 becomes active, batch count value is added 1(Batch count value can be observed by pressing SET1 button). When number of how many times Output-2 is active becomes equal to SET-1 value, then Output-1 becomes active. If Output-1 pulse time Pro-15 is 00000 D , then Output-1 does not change position until manual reset input is active. If Output-1 pulse time Pro-15 is not, then Output-1 becomes inactive at the end of the pulse time.

How it operates in BATCH COUNTER function is explained below:
Counting direction : $\mathbf{0} \Rightarrow \mathrm{P}$ (Upcount)
Pra-19 = 000000


When count value reaches to SET2 value, count value is reset and Output-2 becomes active. If Output-2 pulse time Pro- 17 is 0 Then Output-2 does not change position until manual reset input is active. If Output-2 pulse time $\left[P_{r a-17}\right.$ is not 0 , Output-2 becomes inactive at the end of the pulse time.

When Output-2 becomes active, 1 is added to batch count value is (Batch count value can be observed by pressing SET1 button). When number of how many times Output-2 is active becomes equal to SET1 value, then Output-1 becomes active and Batch count value is reset automatically. If Output-1 pulse time Pro-15 is ODODOD , then Output-1 does not change position until manual reset input is active. If Output-1 pulse time $\operatorname{Pro}^{-15}$ is not 0 , then Output-1 becomes inactive at the end of the pulse time.

Count direction : $\mathrm{P} \Rightarrow \mathbf{0}$ (Downcount)


When count value reaches to ODODO value, count value becomes equal to SET2 value and Output-2 becomes active. If Output-2 pulse time Pro- 17 is DODNDS , then Output-2 does not change position until manual reset input is active. If Output-2 pulse time $P_{r-1}$ - 7 is not 0 , Output-2 becomes inactive at the end of the pulse time.

When Output-2 becomes active, 1 is added to batch count value is (Batch count value can be observed by pressing SET1 button). When number of how many times Output-2 is active becomes equal to SET1 value, then Output-1 becomes active and Batch count value is reset automatically. If Output-1 pulse time Pro-15 is BOUNOS , then Output-1 does not change position until manual reset input is active. If Output-1 pulse time $\operatorname{Pro-15}$ is not 0 , then Output-1 becomes inactive at the end of the pulse time.

Pro-07
Time Out ( Input Signal Reset Time )
(It is accessible only in FREQUENCYMETER / TACHOMETER function)

Actual count value is reset if no signal is applied to Ch-A input for a time which is greater than the value is set in this parameter.
It can be adjusted from DODOD to 0 ODOm is 000000 . Only Ch-A input is performed in Frequencymeter/Tachometer functions

## Pro-08 <br> Measurement Period <br> (It is accessible only in FREQUENCYMETER / TACHOMETER Function)

Number of pulses in Ch-A input is counted during this time It can be adjusted from 0000

This parameter is visible if $\operatorname{Pro-i3}$ measurement method selection parameter is DRDCD . Only Ch-A input is performed in Frequencymeter/Tachometer functions

## $\square-\square-\Gamma$ Output-1 Function <br> (It is accessible only in FREQUENCYMETER / TACHOMETER Function)

FRKKKR Output is latched. Output-1 does not change position until

Output-1 is latched


## 

Output-1 is non-latched


HZGZGG Output-1 is an alarm output. For details, refer to Alarm
(i) Only Ch-A input is performed in Frequencymeter/Tachometer functions

Pro-10
Output-2 Function
(It is accessible only in FREQUENCYMETER / TACHOMETER Function)
777777 Output is latched. Output-2 does not change position until Manual reset is applied.

Output-2 is latched

(i) Only Ch-A input performs in Frequencymeter/ Tachometer function.

## GПTKTG Non-latched with hysteresis output is selected.

Output-2 is non-latched


## $\square 1 \square-11$

Alarm Functions for Output-1
(It is accessible only in FREQUENCYMETER / TACHOMETER Function)
If Output -1 function parameter $P P_{\square-09}$ is selected $\triangle O D O D 2$
Alarm output, then Output-1 becomes active according to this parameter.

Output-1


Count Value

## 

Output-1


Count Value
(i) Only Ch-A input performs in Frequencymeter / Tachometer function.

## 

Output-1


Count Value

## 

Output-1


Count Value

## ㄱNㄱㄴ Deviation Band Alarm.


(i) Only Ch-A input performs in Frequencymeter / Tachometer function.

# $\square \square \square-1 \square$ 

Hysteresis for Output-1 (It is accessible in FREQUENCYMETER / TACHOMETER functions)

It defines hysteresis for Output-1. It is used if Output-1 is non-latched. It can be adjusted from ODODOD to 050200
(i) Only Ch-A input performs in Frequencymeter / Tachometer function.

It defines hysteresis for Output－2．It is used if Output－2 is non－latched． It can be adjusted from 00000 D to 85000
（i）Only Ch－A input performs in Frequencymeter／Tachometer function．


Output－1 Pulse Time
It determines how long Output－1 will be active．
It can be adjusted from 0000.00 to 0099.99 seconds．
If it is 0000.00 second，then it operates indefinitely．
For details，refer to the section where output functions $P$ Pa－DE are defined


Output－2 Pulse Time
It determines how long Output－2 will be active．
It can be adjusted from 0000.00 to 0099.99 seconds．
If it is 0000.00 second，then it operates indefinitely．
For details，refer to the section where output functions $P r a-D 5$ are defined


## Start of the Controlling

（It is accessible only in FREQUENCYMETER／TACHOMETER functions）
Outputs are controlled according to this parameter
ムППワワワ Control is started when the unit is energised．
FTRZG i Control is started when count value reaches to SET1 value
GKTKKa Control is started when count value reaches to SET2 value．

## Pro-19 <br> Direction of Counting <br> (It is accessible in functions except for FREQUENCYMETER/ TACHOMETER functions)

ПППППП Upcount. ( $0 \Rightarrow$ Preset )
ППППП D Downcount. (Preset $\Rightarrow 0$ ) COUNTER / "TOTALIZER COUNTER" functions, then direction of counting parameter $\operatorname{Pro-1]}$ can not be accessed.

$\square$ - - Saving Count Value (Power down back-up)
(It is accessible in functions except for FREQUENCYMETER/ TACHOMETER functions)

OПOППП Count value is saved to memory when power is disconnected and restored on power up.

00000 il
Count value is not saved to memory when power is disconnected. When power up 020005 is shown on the screen.


SET1 Operation Form Selection
（It is accessible only in COUNTER／＂TOTALIZER COUNTER＂ Function）

##  999998

OПONT 1 Operation with offset．SET1 can be defined $\pm$ Offset according to SET2 value．（SET1＝SET1＋SET2 ）

For example ；if operation with offset is selected，SET1＝ 5000，SET2＝ 10000.
Output－1 becomes active or inactive according to
SET1 $=5000+10000=15000$ value

For example；If operation with offset is selected ；
If 6th digit of the SET1 is adjusted to＂－＂，SET1 becomes negative（For details，refer to Section 7．3）
SET1 $=-05000$ ；SET2 $=10000$
Output－1 becomes active or inactive according to
SET1 $=-5000+10000=5000$ value

## Pro－23 <br> Slave Address

Device address for serial communication bus．
It can be adjusted from 00000 to 000247

## $\square \square \square-\square$ I Modbus Protocol Type Selection

##  <br> 

## $\square \square \square-\square \square$ Communication Parity Selection

## 

ИTVTR O Odd Parity
ユワワワワコ Even Parity
Pro－25

#  


～～～～ゥコ 4800 Baud Rate
～～～～Rヨ 9600 Baud Rate
ㄱㄻㄲㄴ 19200 Baud Rate

## $\square \square \square-\square 7$ Communication Stop Bit selection

걔걔 1 Stop Bit

$\square \square \square-\square$ Reset and Set protection（For accessing from front panle）

TMTM Only RESET button protection is active．Actual value can not be reset by Reset button．
Actual value can be reset only reset input is active

ППППワ7 Full protection ；Reset protection is active，also SET1 and SET2 can not be changed．

ムワワワワ4 SET1 can not be changed．


Pro－29
Frequency／Cycle Coefficient
（It is accessible only in FREQUENCYMETER／TACHOMETER functions）

It can be adjusted from 00000 to 09393 ．Count value is multiplied with this parameter．
If it is SDOD multiplication is not performed．So number of pulses are displayed without having any changes．

It can be adjusted from 0 DOD i to 939393 . Changes in this parameter is evaluated when counting starts.
If it is IODOD multiplication is not performed. So number of pulses are displayed without having any changes.

Pro-PS

## Program Password

It is used for accessing to the program parameters. It can be adjusted from DODODO to D59393.
If it is 10000 D , there is no password protection while accessing to the parameters.
When programming button is pressed, Proi will appear on the display.
If program password is not " 0 " while accessing to the program parameters;
1- If user does not enter the P5uurd value correctly ; operation screen will appear without entering to operator parameters.

2- When PSuur in top display and DODOD in bottom display, if user presses ENTER button without entering password (for observing the parameters):
User can see all parameters except Program Password but device does not allow to do any changes with parameters.
( Please refer to Section 9. Failure Messages in EZM-9950 Programmable Timer \& Counter (2) )


1 - Position of the DIP Switch is wrong. (DIP Switch determines the operation function of the device and it is under the top cover)
For details, refer to Section 2.8 "Selection of Operation Function and Input Type with DIP Switch".

2 - If the password is not 0 , user can access to the parameters without entering the password and by pressing ENTER button.
User can see all parameters except for programming password parameter Pro-P5 but user can not do any changes in parameters. If password is entered for accessing to the parameters correctly, most significant digit of the parameter flashes. But if the password is not entered, flashing of the most significant digit is not realised.
 of the parameter

When PROG button is pressed, password entering screen will appear.

## Password Screen

The most significant digit (4th digit for this parameter) flashes.

Press ENTER button without entering the password.


For COUNTER / "TOTALIZER COUNTER" Function


Input Types and Functions

No digit flashes.

By pressing ENTER button, user can see all parameters except for program password

## For COUNTER / "TOTALIZER COUNTER" function

Press PROG button to exit from programming mode.


Continue to press ENTER button for scanning the parameters.


Operation Screen


Input Types and
Functions


3 - If Actual Value is flashing and counting is stopped; It appears if any of the count value is greater than the maximum count value.
(Total count value for Counter/"Totalizer Counter" Function - Batch count value for Batch Counter FUNCTION )
To remove this warning and reset the count value press RESET button.

4 - If actual value is flashing and counting is not performed;
It appears if any of the count value is less than the minimum count value.
(Total count value for Counter/"Totalizer Counter" Function - Batch count value for Batch Counter FUNCTION )
To remove this warning and reset the count value press RESET button.

| Device Type | : Programmable Timer \& Counter |
| :---: | :---: |
| Housing \& Mounting | : $96 \mathrm{~mm} \times 96 \mathrm{~mm} \times 87.5 \mathrm{~mm} 1 / 4$ DIN 43700 plastic housing for panel mounting. Panel cut-out is $92 \times 92 \mathrm{~mm}$ |
| Protection Class | : NEMA 4X (IP65 at front, IP20 at rear). |
| Weight | : Approximately 0.34 Kg . |
| Environmental Ratings | : Standard, indoor at an altitude of less than 2000 meters with none condensing humidity |
| Storage / Operating Temperature: $-40^{\circ} \mathrm{C}$ to $+85{ }^{\circ} \mathrm{C} / 0^{\circ} \mathrm{C}$ to $+50^{\circ} \mathrm{C}$ |  |
| Storage / Operating Humidity | : 90 \% max. (None condensing) |
| Installation | : Fixed installation |
| Over Voltage Category | : II |
| Pollution Degree | : II, office or workplace, none conductive pollution |
| Operating Conditions | : Continuous |
| Supply Voltage and Power | : 100-240 V ~ 50/60 Hz. (-15\% / +10\%) 6VA |
|  | 24 V ~ 50/60 Hz. (-15\% / +10\%) 6VA |
|  | $24 \mathrm{~V}=-\mathrm{l}$ (-15\% / +10\%) 6W |
|  | $12 \mathrm{~V}=-\mathrm{C}$ (-15\% / +10\%) 6W |
| Maximum Input Frequency | : For Counter / "Totalizer Counter" and Batch Counter ; <br> If Pra-Z $=0,1,2 ; 6000 \mathrm{~Hz}$ |
|  | If $\mathrm{Pro-} \mathrm{\square}=3,4 ; 4000 \mathrm{~Hz}$ |
|  | If Pro-D $=5,6 ; 3500 \mathrm{~Hz}$ |
|  | If Pro-D $=7 ; 2000 \mathrm{~Hz}$ |
|  | For Frequencymeter / Tachometer ; 10kHz |
|  | Max 30 Hz (Pro-04 $\neq 0$, debounce) |
| Optional Output Modules | :-EMO-900 Relay Output Module (5A@250V~) -EMO-910 SSR Driver Output |
|  | Module(Max20mA@18V=-) |
|  | -EMO-920 Digital (Transistor) Output Module |
| Standard Communication |  |
| Module | EMC-900 RS-232 Communication Module |
| Optional Communication |  |
| Module | : EMC-910 RS-485 Communication Module |
| Communication Protocol | : MODBUS-RTU, MODBUS-ASCII |
| Process Display | : 14 mm Red 6 digit LED display |
| Set Display | : 9 mm Green 6 digit LED display |
| Led Indicators | : SV1 (Set1 value), SV2 (Set2 value), OP1 / 2 (Control or Alarm Output ) LEDs |

